

4.) VKSU Astable Multivibrator



The operational amplifier operating as free running (astable) Multivibrator is shown in figure - 1

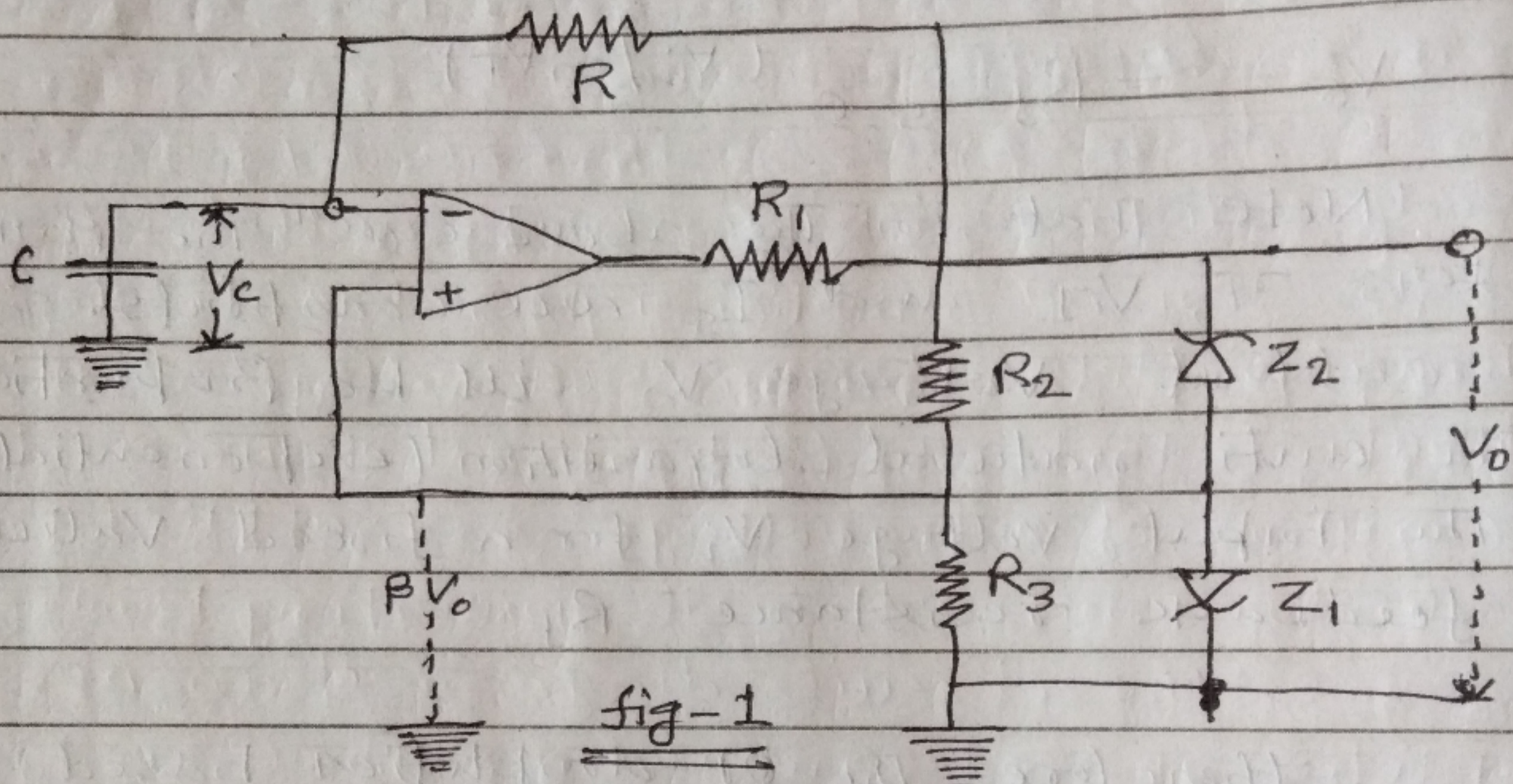


fig-1

Astable Multivibrator

In free running multivibrator, there are two states which remain momentarily stable and the circuit switches repeatedly between these two states. OP-amplifier enjoys both +ve and -ve feedbacks and ~~has~~ has a timing capacitor C, at its inverting input terminal.

The output voltage V_0 is limited by the break down voltage $+V_{0s}$ and $-V_{0s}$ of the two Zener diodes Z_1 and Z_2 connected back to back across the output terminals of the

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OP - amplifier. Thus V_o will be either $+V_{os}$ (or V_{os}^+) or $-V_{os}$ (V_{os}^-). A fraction $\beta = R_3 / (R_2 + R_3)$ of V_o is feedback to the non-inverting input. Thus in one state the amplifier output reaches a +ve saturation level ($V_o = +V_{os}$, diode Z_1) the output waveform in this a square wave figure (2)

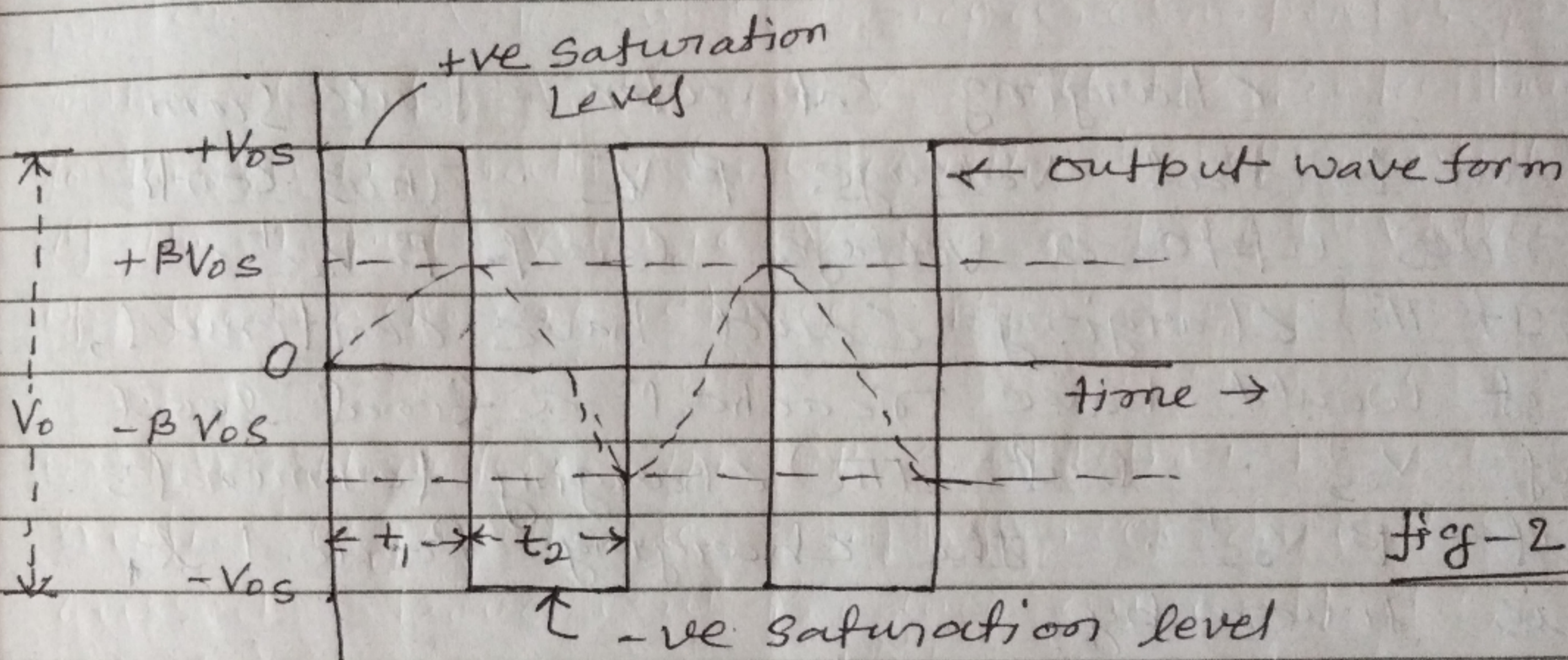


Fig-2

output waveform of free running multivibrator

The input voltage V_{in} to the amplifier is

$$V_{in} = V_c - \beta V_o$$

When $V_{in} < 0$, or $V_c < \beta V_o = \beta V_{os}^+$

Capacitor C charges exponentially towards

V_{os}^+ through a time constant RC . The output

V_o , remains constant at V_{os}^+ until $V_c = \beta V_{os}^+$

So, that $V_{in} = V_c - \beta V_{os}^+ = 0$, i.e. The potential

difference between the two input terminals

approaches zero, and the amplifier output



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reverses to V_{os} . Now C charges exponentially towards V_{os} .

Then $V_i = V_c - \beta V_o = V_c + \beta V_{os}^+$. The output remains constant at V_{os}^-

until $V_c = -\beta V_{os}^-$ at which $V_i = 0$

and the reverse of state takes place.

These waveforms are shown in fig-2.

Charging capacitor starts from an initial voltage βV_{os}^- . This continues upto a voltage level βV_{os}^+ .

If the charging could have continued, it would have reached a final level of V_{os}^+ . But the charging terminates at βV_{os}^+ . The charging period t_1 is given by

$$t_1 = RC \log_e \frac{V_{os}^+ - \beta V_{os}^-}{V_{os}^+ - \beta V_{os}^+}$$

$$= RC \log_e \frac{V_{os}^+ - \beta V_{os}^-}{V_{os}^+ (1 - \beta)}$$

The 2nd charging time from βV_{os}^+ to $-\beta V_{os}^-$ will be

$$t_2 = RC \log_e \frac{V_{os}^- - \beta V_{os}^+}{V_{os}^- (1 - \beta)}$$

If $V_{os}^+ = V$ and $V_{os}^- = -V$ Then $t_1 = t_2$ So that we shall have period

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of one oscillation or time period as

$$T = t_1 + t_2$$

$$= RC \log e \frac{V + \beta V}{V(1 - \beta)} + RC \log e \frac{-V - \beta V}{-V(1 - \beta)}$$

$$= RC \log e \frac{(1 + \beta)}{(1 - \beta)} + RC \log e \frac{(1 + \beta)}{(1 - \beta)}$$

$$= 2 RC \log e \frac{(1 + \beta)}{(1 - \beta)} \quad \text{--- (1)}$$

$$= 2 RC \log e \frac{1 + R_3 / (R_2 + R_3)}{1 - R_3 / (R_2 + R_3)}$$

$$= 2 RC \log e \left[1 + \frac{2R_3}{R_2} \right]$$

If β is chosen to be 0.473 then $T = 2RC$
So that frequency of oscillation is

$$f = \frac{1}{T} = \frac{1}{2RC}$$

From equⁿ (1), we observe that time period is independent of saturation level V_{os}^+ and V_{os}^- and depends only on time constant RC and feedback factor B .

A stable multivibrator is very useful for fixed frequency applications in audio frequency range (10 c/s - 10 kc/s). At frequencies greater than 10 kc/s, the delay time of the amplifier for going from one

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state of saturation to another state of saturation becomes significant further, slew rate of OP-amplifiers also sets a limit on the ~~rise~~ rise and fall times of square wave output waveform.